Mythology:

Step-1: Take ESP32 with cam and connected with Arduino

Step-2: Using CAM in ESP32 and store in a memory card. And then data of video will be taken from memory card.

Step-3: Take entire system to top by using any fly machine like balloons or drone.

Step-4: Data collected will be processed by using OpenCV2 module and the features will be redrived and all required features will be extracted.

Step -5: Now we will create a machine learning model by a Linear recursion Algorithm

Step-6: Machine learning algorithms required data .Data of features of and there classification. We are using persons, mountains ,rivers, buildings , cars and motor vehicles, trucks etc.

Step-7: Now based on features a bounding box is created and labelled it with the particular object.

Step-8: As we will get the video with bounding box and labelled.